

10-701 Recitation:

Probabilistic and graphical models

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Probabilistic modeling

- There are a lot of different naming conventions.
 - Seems to be the case a lot in machine learning
 - and outside machine learning as well...
- I will present some definitions using nomenclature that I think is intuitive, but also not far off from what other people use.

What is a **probabilistic model**?

Probabilistic modeling

A **probabilistic model** is a collection of random variables.

The random variables can be divided into two categories:

1. the **observations** (data)
2. the **hidden variables**

Intuitively, a probabilistic model is a *description* of how your observations were generated.

It can be a hypothesis of the mechanism that underlies your data.

Probabilistic modeling

For more intuition, imagine we have a system of equations.

$$x + 2y = 4$$

If x is 0, what is y ?

If $x \sim \mathcal{N}(0,1)$, what is y ?

You can think of a probabilistic model as a system where the variables can be random.

Probabilistic modeling

A **probabilistic model** is a collection of random variables: $\{\mathbf{x}, \boldsymbol{\theta}\}$

The random variables can be divided into two categories:

1. $\mathbf{x}$: the **observations** (data)
2. $\boldsymbol{\theta}$: the **hidden variables**

the **prior** distribution is $p(\boldsymbol{\theta})$

the **likelihood** is $p(\mathbf{x}|\boldsymbol{\theta})$

the **posterior** distribution is $p(\boldsymbol{\theta}|\mathbf{x})$

the **joint** distribution is $p(\mathbf{x}, \boldsymbol{\theta})$

So then, what's a graphical model?

A **graphical model** is a graphical representation of a probabilistic model.

There are different ways to represent probabilistic models graphically:

- Bayesian networks
- Factor graphs
- Markov random fields

When people say “graphical model”, they usually mean

graph + probabilistic model.

Common convention: **observations** are depicted as shaded nodes, whereas **hidden variables** are unshaded.

Example

probabilistic model

$w \sim \text{Uniform}(0,1)$

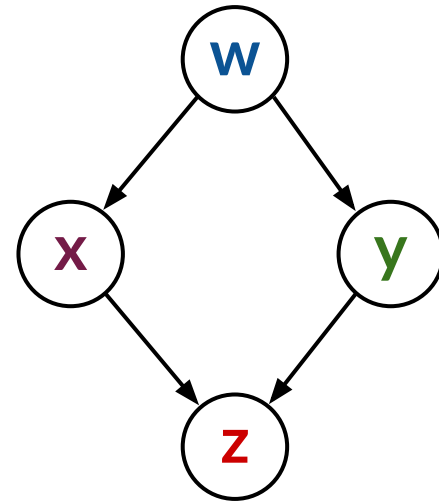
$x \sim \text{Bernoulli}(w)$

$y \sim \text{Bernoulli}(w)$

$$z = x + y$$

You can think of x and y as two coin flips, and w represents the fairness of the coin.

graphical model

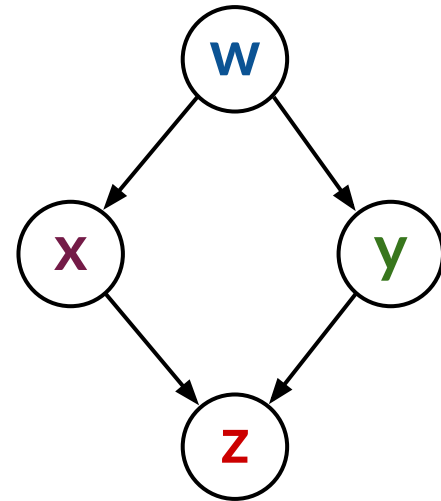


Example

It is easy to factorize the joint distribution by looking at the graph structure:

$$p(\mathbf{w}, \mathbf{x}, \mathbf{y}, \mathbf{z}) = p(\mathbf{w})p(\mathbf{x}|\mathbf{w})p(\mathbf{y}|\mathbf{w})p(\mathbf{z}|\mathbf{x}, \mathbf{y})$$

graphical model



Example

$$\mathbf{w} \sim \text{Uniform}(0,1)$$

$$\mathbf{x} \sim \text{Bernoulli}(\mathbf{w})$$

$$\mathbf{y} \sim \text{Bernoulli}(\mathbf{w})$$

$$\mathbf{z} = \mathbf{x} + \mathbf{y}$$

What is $p(\mathbf{x}|\mathbf{w})$?

$$p\{\mathbf{x} = 0|\mathbf{w}\} = 1 - \mathbf{w} \text{ and } p\{\mathbf{x} = 1|\mathbf{w}\} = \mathbf{w}$$

$$p\{\mathbf{y} = 0|\mathbf{w}\} = 1 - \mathbf{w} \text{ and } p\{\mathbf{y} = 1|\mathbf{w}\} = \mathbf{w}$$

What is $p(\mathbf{z}|\mathbf{x},\mathbf{y},\mathbf{w}) = p(\mathbf{z}|\mathbf{x},\mathbf{y})$?

$$p(\mathbf{z}|\mathbf{x},\mathbf{y}) = \delta\{\mathbf{z} = \mathbf{x} + \mathbf{y}\}$$

What if we want to get rid of $\mathbf{x}$ and $\mathbf{y}$? We can **marginalize** out $\mathbf{x}$ and $\mathbf{y}$.

Lets compute $p(\mathbf{z}|\mathbf{w})$.

Example

$\mathbf{w} \sim \text{Uniform}(0,1)$

$\mathbf{x} \sim \text{Bernoulli}(\mathbf{w})$

$\mathbf{y} \sim \text{Bernoulli}(\mathbf{w})$

$\mathbf{z} = \mathbf{x} + \mathbf{y}$

$$\begin{aligned} p\{z = 0|w\} &= \sum_{x \in \{0,1\}} p\{z = 0|x, w\}p(x|w), \\ &= \sum_{x \in \{0,1\}} \sum_{y \in \{0,1\}} p\{z = 0|x, y, w\}p(x|w)p(y|w), \\ &= \sum_{x \in \{0,1\}} \sum_{y \in \{0,1\}} \delta\{x = 0, y = 0\}p(x|w)p(y|w), \\ &= p\{x = 0|w\}p\{y = 0|w\}, \\ &= (1 - w)^2. \end{aligned}$$

Example

$$\mathbf{w} \sim \text{Uniform}(0,1)$$

$$\mathbf{x} \sim \text{Bernoulli}(\mathbf{w})$$

$$\mathbf{y} \sim \text{Bernoulli}(\mathbf{w})$$

$$\mathbf{z} = \mathbf{x} + \mathbf{y}$$

Repeating the process for the other possible values of $\mathbf{z}$:

$$p\{\mathbf{z} = 0 | \mathbf{w}\} = (1 - \mathbf{w})^2$$

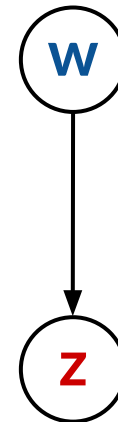
$$p\{\mathbf{z} = 1 | \mathbf{w}\} = 2\mathbf{w}(1 - \mathbf{w})$$

$$p\{\mathbf{z} = 2 | \mathbf{w}\} = \mathbf{w}^2$$

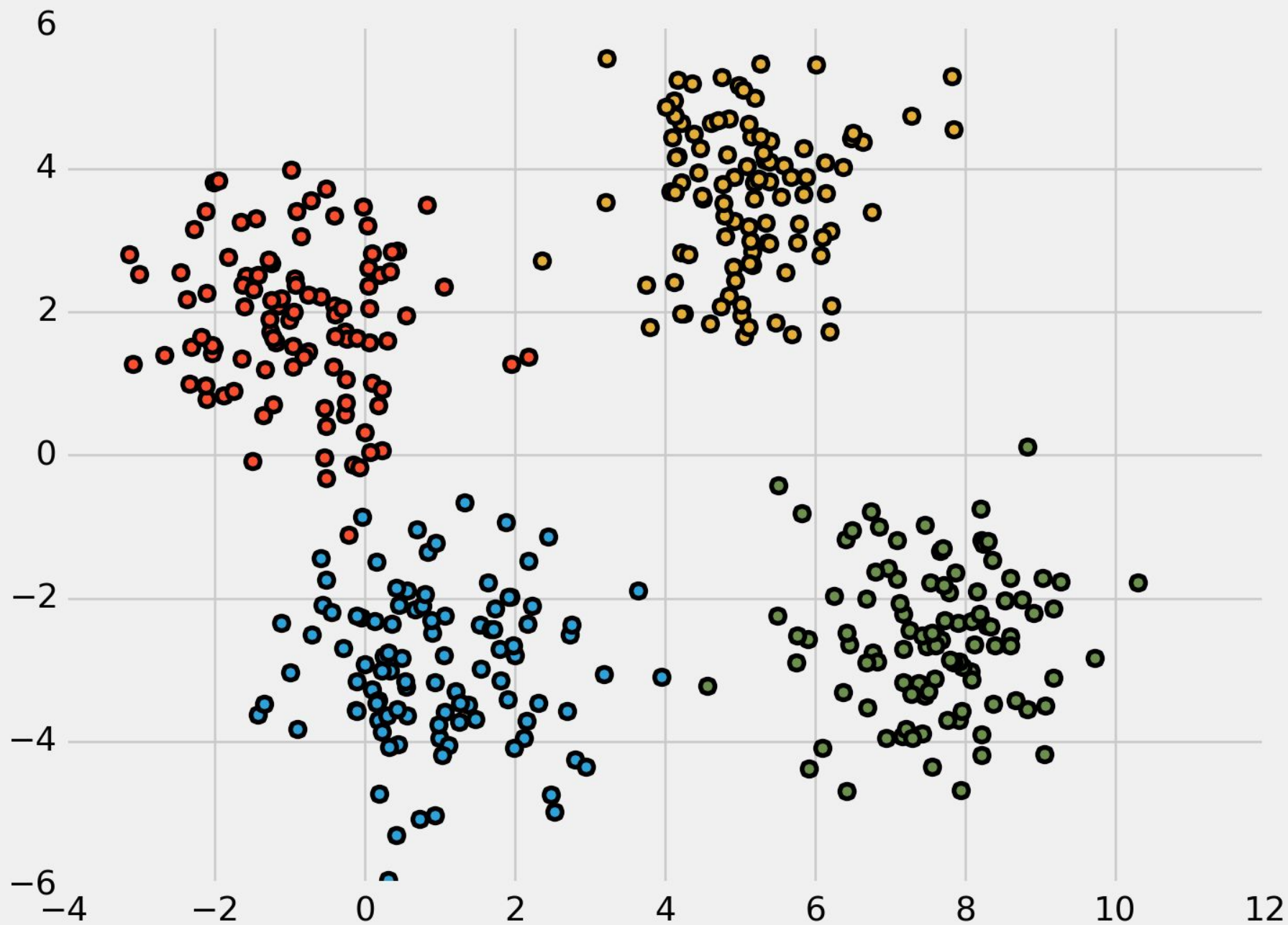
This is a new model:

$$\mathbf{w} \sim \text{Uniform}(0,1)$$

$$\mathbf{z} \sim \text{the above discrete distribution}$$



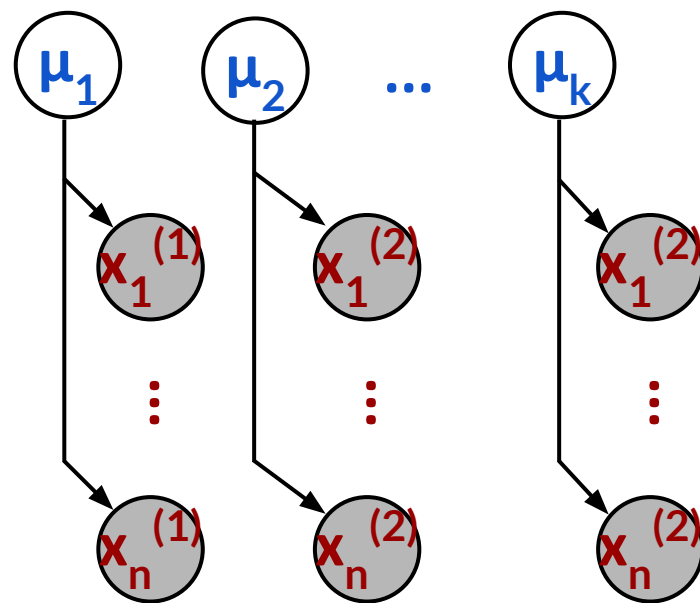
The reasoning and intuition behind variable elimination and belief propagation is the same.



What is a good probabilistic model for this data?

The points look like they came from four normal distributions.

$$\begin{aligned}\mu_1, \dots, \mu_k &\sim \mathcal{N}(0, 10I), \\ x_1^{(1)}, \dots, x_n^{(1)} &\sim \mathcal{N}(\mu_1, I), \\ x_1^{(2)}, \dots, x_n^{(2)} &\sim \mathcal{N}(\mu_2, I), \\ &\text{and so on} \dots \text{for } k \text{ clusters}\end{aligned}$$



For simplicity, we fixed the covariances to the identity. If desired, you could make them unknown variables and use, for instance, an inverse-Wishart prior (see last week's recitation resources).

We can re-write this model:

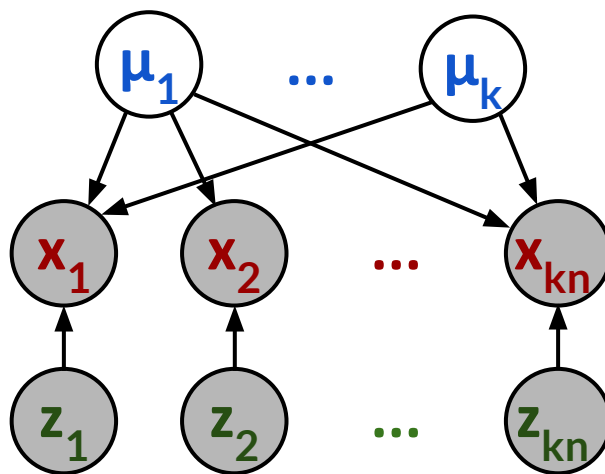
$$\mu_1, \dots, \mu_k \sim \mathcal{N}(0, 10I),$$

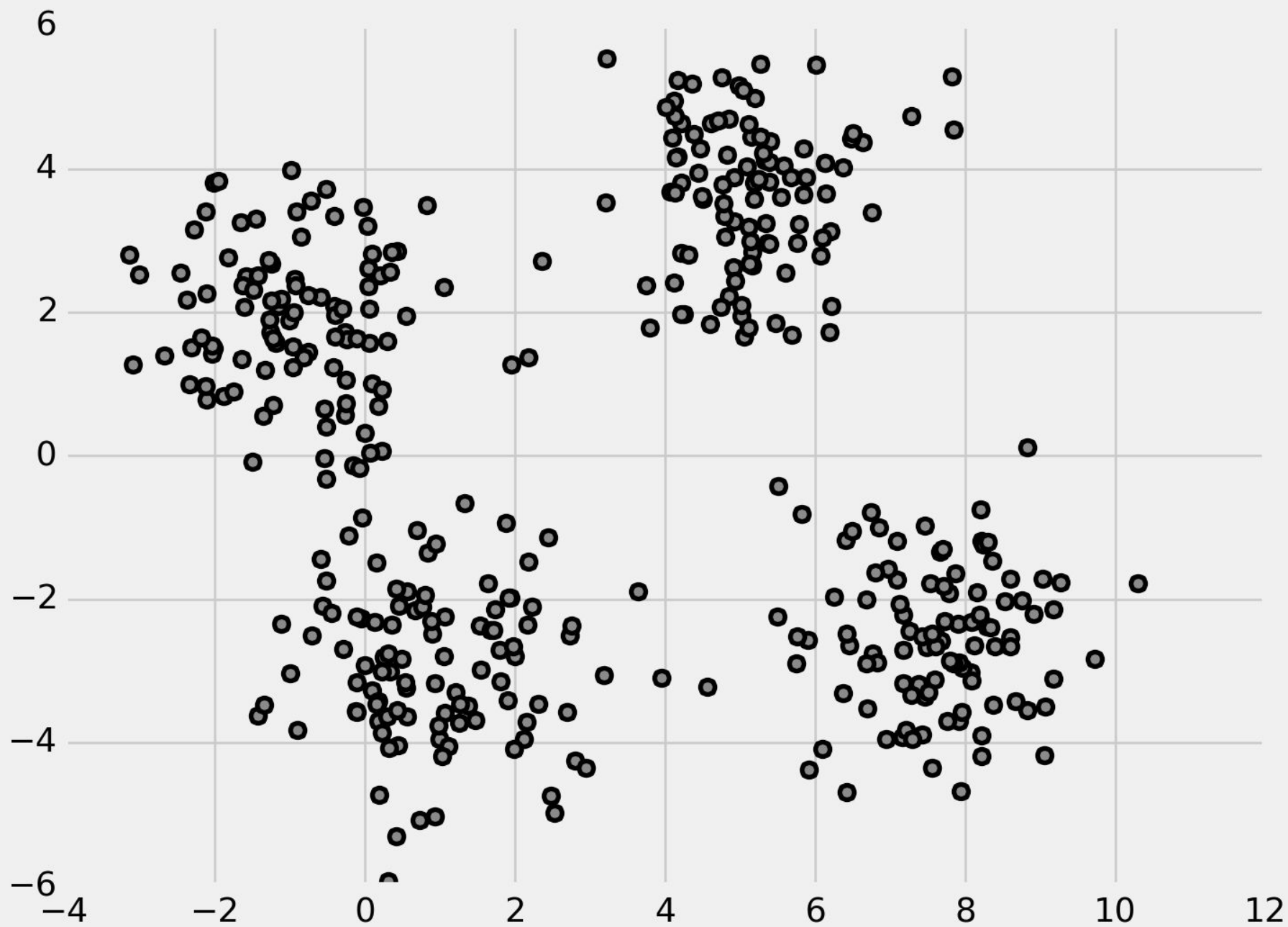
$$z_1, \dots, z_n = 1,$$

$$z_{n+1}, \dots, z_{2n} = 2,$$

etc...

$$x_i \sim \mathcal{N}(\mu_{z_i}, I) \text{ i.i.d. } i = 1, \dots, kn.$$





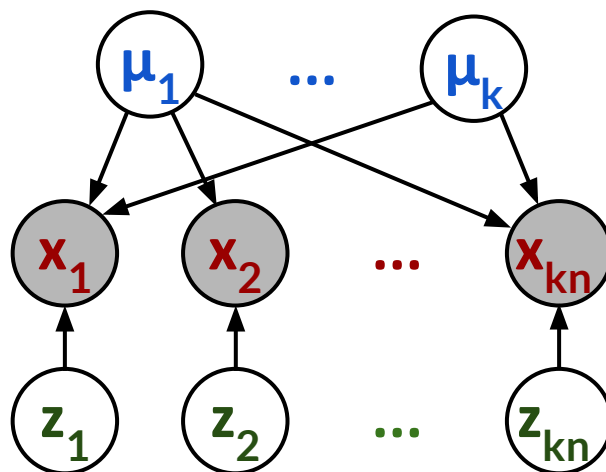
What is a good model for this data?

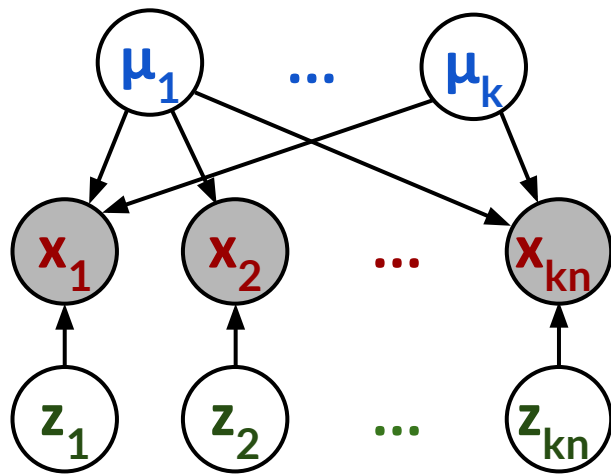
We no longer have knowledge of the class assignments $\mathbf{z}$.

$$\mu_1, \dots, \mu_k \sim \mathcal{N}(0, 10I),$$

$$z_i = \text{Categorical}(\pi),$$

$$x_i \sim \mathcal{N}(\mu_{z_i}, I) \text{ i.i.d. } i = 1, \dots, kn.$$





$$\mu_1, \dots, \mu_k \sim \mathcal{N}(0, 10I),$$

$$z_i = \text{Categorical}(\pi),$$

$$x_i \sim \mathcal{N}(\mu_{z_i}, I) \text{ i.i.d. } i = 1, \dots, kn.$$

Let's try to do inference using MAP in this model. Write the log-posterior: $\log p(\mu_1, \dots, \mu_k, z_1, \dots, z_{kn} | x_1, \dots, x_{kn})$.

$$\log p(\boldsymbol{\mu}, \mathbf{z} | \mathbf{x}) = \log p(\mathbf{x} | \boldsymbol{\mu}, \mathbf{z}) + \log p(\boldsymbol{\mu}) + \log p(\mathbf{z}) + C,$$

$$= \sum_{i=1}^{kn} \log p(x_i | \boldsymbol{\mu}, z_i) + \sum_{j=1}^k \log p(\mu_j) + \sum_{i=1}^{kn} \log p(z_i),$$

$$= -\frac{1}{2} \sum_{i=1}^{kn} (x_i - \mu_{z_i})^\top (x_i - \mu_{z_i}) - \frac{1}{20} \sum_{j=1}^k \mu_j^\top \mu_j + \sum_{i=1}^{kn} \log \pi_{z_i}.$$

Expectation maximization (EM)

- If we knew either μ or z , then MLE/MAP would be easier.
- EM is an inference algorithm for computing MLE or MAP.
- Given any probabilistic model with observations x and hidden variables θ , we first subdivide the hidden variables θ into two classes: z and μ .
- Start with a guess for μ .

E step. compute the expectation using our current estimate of μ :

$$q(\mu) = E_{p(z|x, \mu^*)}[\log p(\mu, z|x)]$$

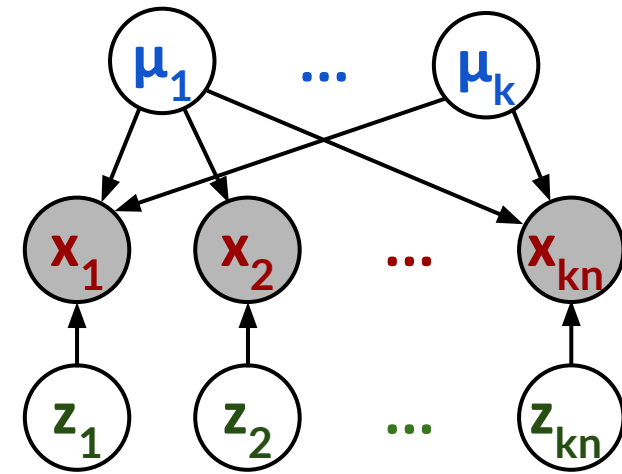
M step. update the estimate of μ^* by maximizing $q(\mu)$:

$$\mu^* = \arg \max q(\mu)$$

Repeat until convergence.

Expectation maximization

- We need to compute $p(\mathbf{z}|\mathbf{x}, \boldsymbol{\mu})$ to do the E step.



$$p(\mathbf{z}|\mathbf{x}, \boldsymbol{\mu})p(\mathbf{x}, \boldsymbol{\mu}) = p(\mathbf{x}, \mathbf{z}, \boldsymbol{\mu}),$$

$$p(\mathbf{z}|\mathbf{x}, \boldsymbol{\mu}) = p(\mathbf{x}|\mathbf{z}, \boldsymbol{\mu})p(\boldsymbol{\mu})p(\mathbf{z})/p(\mathbf{x}, \boldsymbol{\mu}),$$

$$\log p(\mathbf{z}|\mathbf{x}, \boldsymbol{\mu}) = \log p(\mathbf{x}|\mathbf{z}, \boldsymbol{\mu}) + \log p(\mathbf{z}) + C,$$

$$\log p\{z_i = j|\mathbf{x}, \boldsymbol{\mu}\} = \log p(x_i|z_i = j, \mu_j) + \log p\{z_i = j\} + C,$$

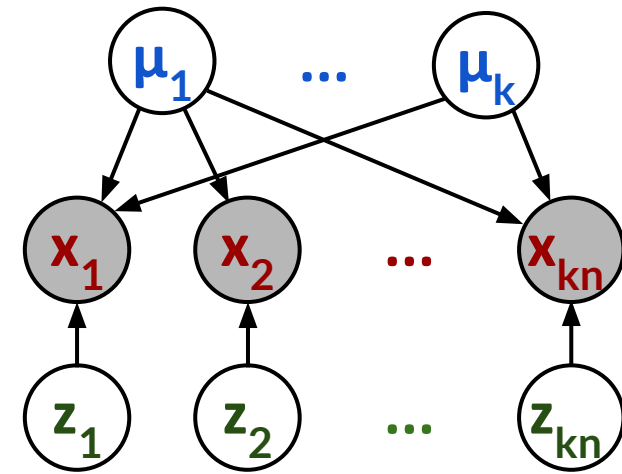
$$= -\frac{1}{2}(x_i - \mu_j)^\top (x_i - \mu_j) + \log \pi_j + C,$$

$$p\{z_i = j|\mathbf{x}, \boldsymbol{\mu}\} \propto \pi_j \exp \left\{ -\frac{1}{2}(x_i - \mu_j)^\top (x_i - \mu_j) \right\}.$$

Expectation maximization

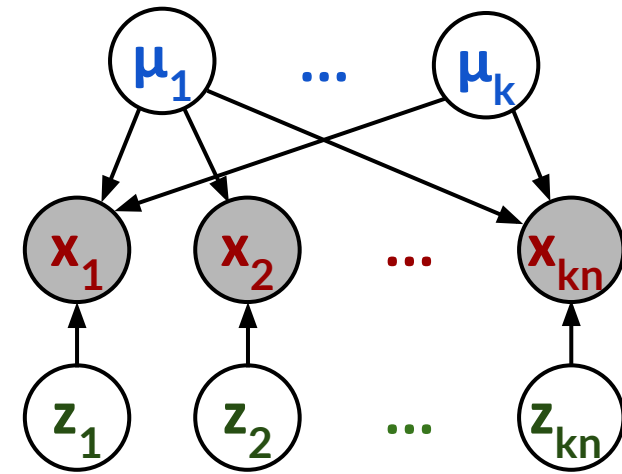
- We can use $p(\mathbf{z}|\mathbf{x}, \boldsymbol{\mu})$ to compute q .

$$\begin{aligned}
 q(\boldsymbol{\mu}) &= \mathbb{E}_{p(\mathbf{z}|\mathbf{x}, \boldsymbol{\mu}^*)} [\log p(\boldsymbol{\mu}, \mathbf{z}|\mathbf{x})], \\
 &= \mathbb{E}_{p(\mathbf{z}|\mathbf{x}, \boldsymbol{\mu}^*)} [\log p(\mathbf{x}|\boldsymbol{\mu}, \mathbf{z})] + \log p(\boldsymbol{\mu}) + C, \\
 &= \sum_{i=1}^{kn} \mathbb{E}_{p(z_i|\mathbf{x}, \boldsymbol{\mu}^*)} [\log p(x_i|\boldsymbol{\mu}, z_i)] + \log p(\boldsymbol{\mu}) + C, \\
 &= -\frac{1}{2} \sum_{i=1}^{kn} \mathbb{E}_{p(z_i|\mathbf{x}, \boldsymbol{\mu}^*)} [(x_i - \mu_{z_i})^\top (x_i - \mu_{z_i})] + \log p(\boldsymbol{\mu}) + C, \\
 &= -\frac{1}{2} \sum_{i=1}^{kn} \sum_{j=1}^k p\{z_i = j|\mathbf{x}, \boldsymbol{\mu}^*\} (x_i - \mu_j)^\top (x_i - \mu_j) + \log p(\boldsymbol{\mu}) + C, \\
 q(\mu_j) &= -\frac{1}{2} \sum_{i=1}^{kn} p\{z_i = j|\mathbf{x}, \boldsymbol{\mu}^*\} (x_i - \mu_j)^\top (x_i - \mu_j) - \frac{1}{20} \mu_j^\top \mu_j + C.
 \end{aligned}$$



Expectation maximization

- Now, for the M step, we just maximize q .



$$\mu_j^* = \arg \max_{\mu_j} q(\mu_j),$$

$$\frac{\partial q}{\partial \mu_j} = \sum_{i=1}^{kn} p\{z_i = j | \mathbf{x}, \boldsymbol{\mu}^*\} (x_i - \mu_j) - \frac{1}{10} \mu_j,$$

$$0 = \sum_{i=1}^{kn} p\{z_i = j | \mathbf{x}, \boldsymbol{\mu}^*\} x_i - \mu_j^* \left(\frac{1}{10} + \sum_{i=1}^{kn} p\{z_i = j | \mathbf{x}, \boldsymbol{\mu}^*\} \right),$$

$$\mu_j^* = \left(\frac{1}{10} + \sum_{i=1}^{kn} p\{z_i = j | \mathbf{x}, \boldsymbol{\mu}^*\} \right)^{-1} \sum_{i=1}^{kn} p\{z_i = j | \mathbf{x}, \boldsymbol{\mu}^*\} x_i$$

